

# Dynamic Programming Algorithms for Some Problems

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Reference clrs, Chapter 15

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## Approach: Dynamic Programming

**Dynamic Programming:** is a general technique which can be used to solve many optimization problems that exhibit **optimal sub-structure**. That is, an optimal solution to the problem contains within it optimal solution to sub-problems.

*Solution of a large problem can be found by examining the solution of smaller sub-problems.*

Reference clrs, Chapter-15, Page-339

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## List Of Some Example Problems

1.	Assembly Line Scheduling	clrs 324-
2.	Matrix Multiply	clrs 331-
3.	Longest Common Subsequence	clrs 350-
4.	0-1 Knap Sack	clrs 382-, and Udi Manber 108-
5.	Optimal Polygon Triangulation	
6.	Optimal Binary Search Tree	clrs 356
7.	Edit Distance	clrs 364 Udi Manber 156-

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## Approach: Dynamic Programming

### **Problem: Assembly Line Scheduling:**

There are two assembly lines, each with  $n$  stations. Find the fastest way through the factory.

Notation:

$a_{i,j}$ : assembly time at station  $S_{i,j}$

$t_{i,j}$ : transfer time from assembly line  $i$  to  $j$  after station  $S_{i,j}$ .

Reference clrs page 324 Chapter-15

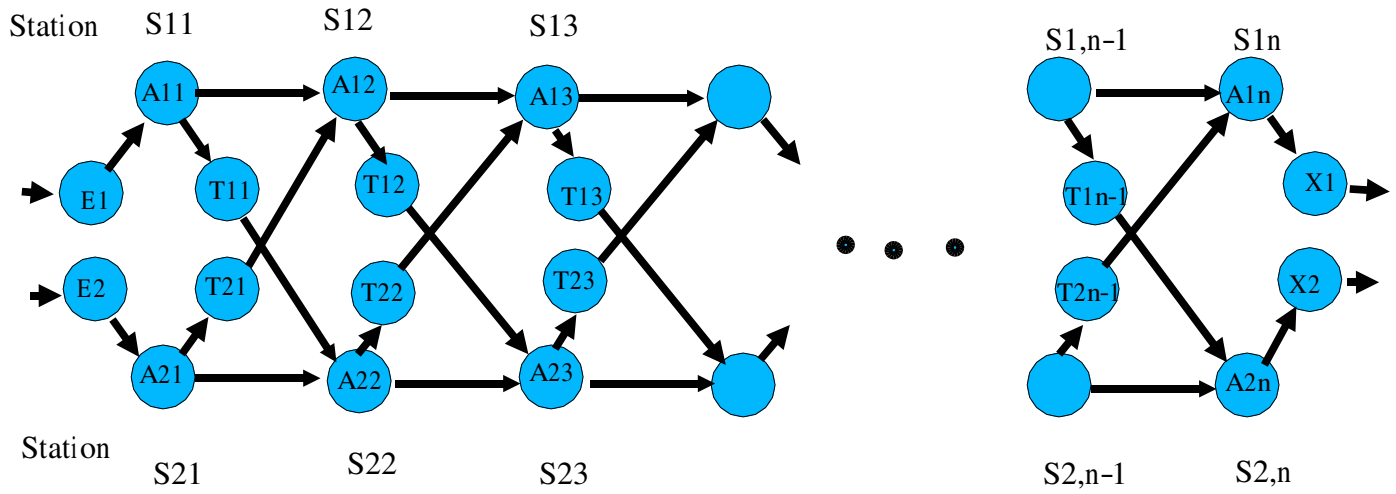
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# Notation: Assembly Line Scheduling:



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## Recurrence Equation: Assembly Line Scheduling:

$$f_1[j] = \begin{cases} e_1 + a_{1,1} & \text{if } j = 1 \\ \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j}) & \text{if } j \geq 2 \end{cases}$$

$$f_2[j] = \begin{cases} e_2 + a_{2,1} & \text{if } j = 1 \\ \min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j}) & \text{if } j \geq 2 \end{cases}$$

Reference clrs page 328 Chapter-15

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## Approach: Dynamic Programming

### **Problem: Sequencing the Multiplication of Matrices:**

To multiply  $n$  matrices

$$A = A_1 \times A_2 \times A_3 \times \dots \times A_n$$

where each  $A_i$  has  $r_{i-1}$  rows and  $r_i$  columns, the problem is to determine the sequence in which the matrices should be multiplied so that the number of multiplications is minimum over all sequences.

Note: we are not actually multiplying the matrices, the goal is to determine the order.

Reference clrs page 331 Chapter-16

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## Approach: Dynamic Programming

### Example: Sequencing the Multiplication of Matrices:

To multiply 3 matrices  $\langle A_1, A_2, A_3 \rangle$  of dimensions  $10 \times 100$ ,  $100 \times 5$  and  $5 \times 50$  if they are multiplied according to parenthesization  $(A_1, A_2), A_3$  there are a total of 7500 multiplications; whereas if they are multiplied according to  $(A_1(A_2, A_3))$  there are 75000 multiplications. Thus the multiplication according to first parenthesization is ten times faster.

Conclusion: The order in which the matrices are multiplied can have a significant effect on the total number of multiplication operations required to find  $A$

Reference clrs page 332 Chapter-16

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## Approach: Dynamic Programming

### Recurrence: Sequencing the Multiplication of Matrices:

Let  $m[i, j]$  be the **minimum cost** (number of scalar multiplications) needed to compute the matrix  $A_{i\dots j}$ . For the full problem the cost to compute  $A_{1\dots n}$  would be  $m[1, n]$ . The recursive equation is :

$$m[i, j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \leq k < j} \{m[i, k] + m[k + 1, j] + p_{i-1}p_kp_j\} & \text{if } i < j \end{cases}$$

The term  $m[i, k]$  is the minimum cost of evaluating

$A_{i\dots k} = A_i \times A_{i+1} \times \dots \times A_k$  and

$m[k + 1, j]$  is the cost of evaluating

$A_{k+1\dots j} = A_{k+1} \times A_{k+2} \times \dots \times A_j$ .

The third term is the cost of multiplying these two matrices.

Reference clrs page 334 Chapter-16

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## Approach: Dynamic Programming

### **Problem: Longest Common Subsequence:**

Given two sequences :

$X = \langle x_1, x_2, \dots, x_m \rangle$  and

$Y = \langle y_1, y_2, \dots, y_n \rangle$

Find a maximum length common subsequence of  $X$  and  $Y$ .

note: skipping is allowed when finding common subsequence. It is not a "consecutive" subsequence.

Reference clrs page 350 Chapter-15

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## Approach: Dynamic Programming

### **Problem: Longest Common Subsequence:**

**Example:** A strand of DNA of one organism may be:

*ACCGGTTCGAGTGCGCGGAAGCCGGCCGAA*

and the DNA of another organism may be:

*GTCGTTCCGGAATGCCGTTGCTCTGTAA*

and the goal of comparing two strands of DNAs is to determine how "similar" two DNAs are, as a measure of how closely related two organisms are.

Reference clrs page 350 Chapter-15

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## Approach: Dynamic Programming

### Problem: Longest Common Subsequence:

#### Theorem:

Let  $X = \langle x_1, x_2, \dots, x_m \rangle$  and

$Y = \langle y_1, y_2, \dots, y_n \rangle$

be two sequences, and let

$Z = \langle z_1, z_2, \dots, z_k \rangle$  be LCS of  $X$  and  $Y$  then:

1. if  $x_m = y_n$  then  $z_k = x_m = y_n$  **and**  
 $Z_{k-1} = LCS(X_{m-1}, Y_{n-1})$
2.  $x_m \neq y_n$  and  $x_m \neq z_k$   
**then**  $Z = LCS(X_{m-1}, Y)$
3.  $x_m \neq y_n$  and  $y_n \neq z_k$   
**then**  $Z = LCS(X, Y_{n-1})$

Reference clrs page 350 Chapter-15

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## Approach: Dynamic Programming

**Problem: Longest Common Subsequence:**

**Observation:** To find LCS of  $X$  and  $Y$  we need to find the LCS of  $X$  and  $Y_{n-1}$  and also LCS of  $X_{m-1}$  and  $Y$ . But each of subproblems in turn have sub-subproblems of find LCS of  $X_{m-1}$  and  $Y_{n-1}$ .

**Conclusion:** When solutions of subproblems share solution of sub-subproblems don't re-compute them just store them away.

Reference clrs page 350 Chapter-15

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## Approach: Dynamic Programming

### Problem: Longest Common Subsequence:

Let  $c[i, j]$  be the **length** of LCS of sequences  $X_i$  and  $Y_j$  then the following recursive formulae hold.

$$c[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ c[i - 1, j - 1] + 1 & \text{if } i, j > 0 \text{ and } x_i = y_j \\ \max(c[i - 1, j], c[i, j - 1]) & \text{if } i, j > 0 \text{ and } x_i \neq y_j \end{cases}$$

Reference clrs page 350 Chapter-15

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## Approach: Dynamic Programming

### **Problem: KnapSack:**

Given an integer  $K$  (say the size of the knapsack), and  $n$  items of different sizes such that the  $i^{th}$  item has an integer size  $S[i]$ , find a subset of the items whose sizes sum to exactly  $K$ , or determine that no such subset exists.

Note: in a 0-1 knap sack either the item is picked or not picked. There is no fractional amount of item which can be picked.

Reference Udi Manber page 108-100 for 0-1 knapsack  
Reference clrs page 382 Chapter-15 for fractional knapsack

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**Algorithm Knap\_Sack**( $S, K$ )

**Input:**  $S$  (an array of size  $n$  storing the sizes of the items)  
 $K$  (the size of the KnapSack)

**Output:**  $P$  (a two dimensional array such that  
 $P[i, k].exist = true$  if there exists  
a solution to the knapsack problem with  
first  $i$  items and a knapsack of size  $k$   
 $P[i, k].belong = true$  if the  $i^{th}$   
element belongs to that solution )

Reference Udi Manber page 108-110

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## Algorithm Knap\_Sack( $S, K$ )

**begin**

$P[0, 0].exist = true;$

**for**  $k = 1$  to  $K$  **do**

$P[0, k].exist = false;$

{comment –there is no need to initialize

$P[i, 0]$  for  $i \geq 1$  it will be computed from  $P[0, 0]$ }

**for**  $i = 1$  to  $n$  **do** {comment –for each item}

**for**  $k = 0$  to  $K$  **do** {comment–for each incremental size}

$P[i, k].exist = false;$  {comment –the default value}

**if**  $P[i - 1, k].exist$  **then**

$P[i, k].belong = false;$

$P[i, k].exist = true;$

//there is no solution with any selection from fir

**else if**  $k - S[i] \geq 0$  **then**

**if**  $P[i - 1, k - S[i]].exist$  **then**

$P[i, k].exist = true;$

$P[i, k].belong = true;$

**end.**

Reference Udi Manber page 108–110

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## Approach: Dynamic Programming

### **Problem: Optimal Polygon Triangulation:**

Given a **Convex** polygon

$P = \langle v_0, v_1, \dots, v_{n-1} \rangle$  and a weight function  $w$  defined on triangles formed by sides and chords of  $P$ . The Optimal Polygon Triangulation problem is to find a triangulation that minimizes the sum of the weights in the triangulation.

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## Approach: Dynamic Programming

**Problem: Optimal Polygon Triangulation:**

One weight function  $w$  on triangles is:

$$w(\Delta v_i v_j v_k) = |v_i v_j| + |v_j v_k| + |v_i v_k|$$

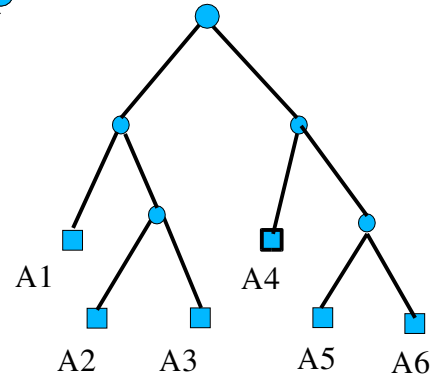
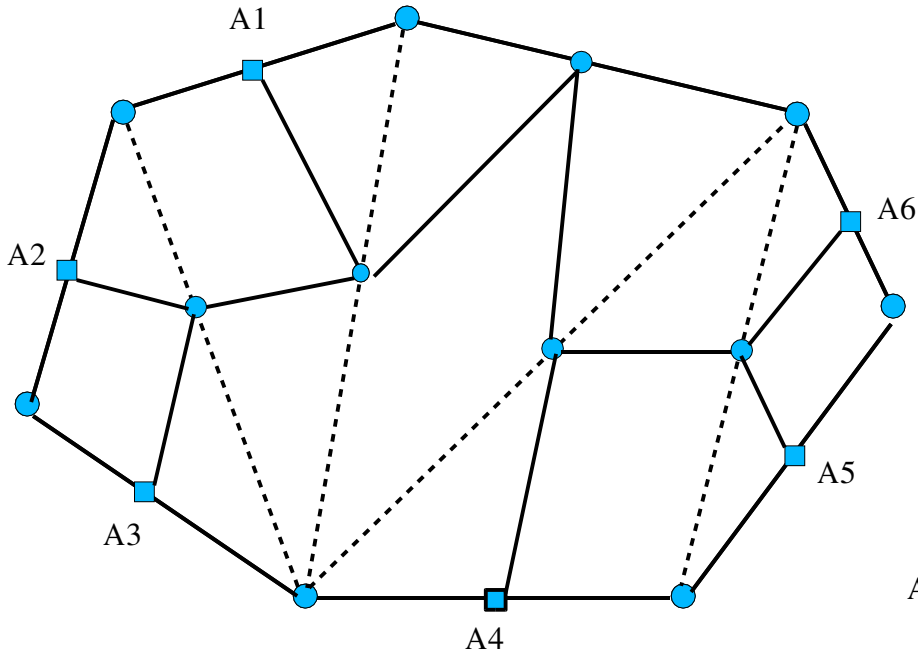
where  $|v_i v_j|$  denotes the Euclidean distance from  $v_i$  to  $v_j$ .

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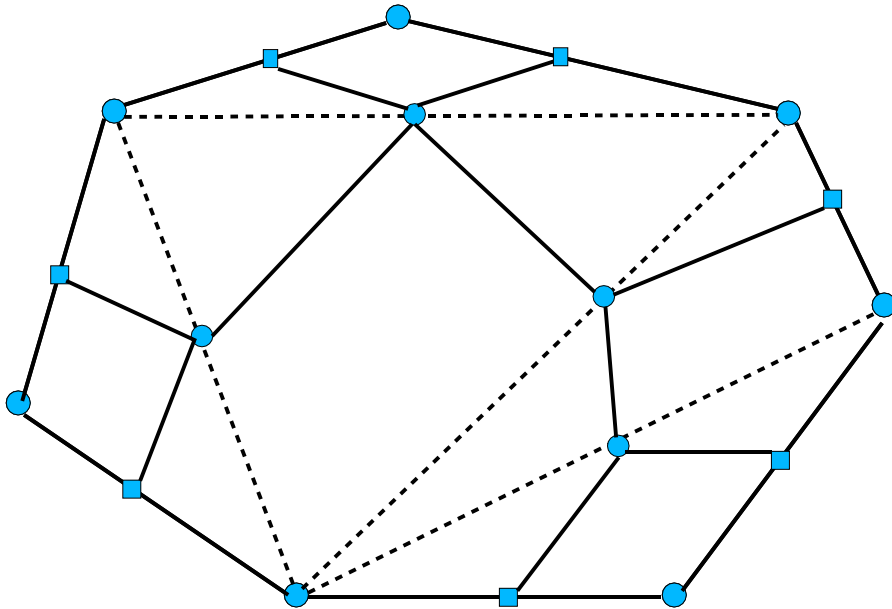
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# Example: Optimal Triangulation:



$((A1(A2,A3))(A4(A5,A6)))$



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## Approach: Dynamic Programming

### Problem: Minimum Edit Distance:

Given two strings

$A = \{a_1, a_2, \dots, a_n\}$ , and

$B = \{b_1, b_2, \dots, b_m\}$

and the cost of transformation operations such as copy, insert, delete, and replace, the **edit distance** from  $A$  to  $B$  is the cost of transformation sequence that transforms  $A$  to  $B$ .

The 'Minimum Edit Distance' problem is to find the edit distance with the least cost.

Reference Udi Manber page 155-158

Reference clrs page 364 Chapter-15

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## **Approach: Dynamic Programming**

### **Example: Minimum Edit Distance:**

In the example following transformation-operations are used:

- **Copy:**
- **Replace:**
- **Delete:**
- **Insert:**
- **Twiddle:**
- **Kill:**

Reference Udi Manber page 155-158

Reference clrs page 364 Chapter-15

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## Approach: Dynamic Programming

### Example: Minimum Edit Distance:

A source string `algorithm` is transformed to a target string `altruistic` by following sequence of transformations:

operation	x	z
<i>initial string</i>	<u>a</u> lgorithm	_
copy	a <u>l</u> gorithm	a_
copy	al <u>g</u> orithm	al_
replace by t	al <u>g</u> orithm	alt_
delete	algor <u>h</u> ithm	alt_
copy	algori <u>t</u> h	altr_
insert u	algori <u>t</u> h	altru_
insert i	algori <u>t</u> h	altrui_
insert s	algori <u>t</u> h	altruis_
twiddle	algori <u>t</u> h	altruisti_
insert c	algori <u>t</u> h	altruistic_
kill	algori <u>t</u> h_	altruistic

The cost of transformation is

$$(3 \cdot \text{cost}(\text{copy})) + \text{cost}(\text{replace}) + \text{cost}(\text{delete}) + (4 \cdot \text{cost}(\text{insert})) + \text{cost}(\text{twiddle}) + \text{cost}(\text{kill})$$

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## Approach: Dynamic Programming

We consider all the different possibilities of constructing the minimum change from  $A$  to  $B$  with the aid of best changes of smaller sequences involving  $A$  and  $B$ .

$A(i)$  denotes the prefix string  $a_1, a_2, \dots, a_i$  and

$B(j)$  denotes the prefix string  $b_1, b_2, \dots, b_j$ .

$C(i, j)$  denotes the minimum cost of changing  $A(i)$  to  $B(j)$ .

and Denote

$$m[i, j] = \begin{cases} 0 & \text{if } a_i = b_j \\ 1 & \text{if } a_i \neq b_j \end{cases}$$

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Three transformations (plus one do nothing) are considered.

delete:

if  $a_n$  is deleted in the minimum change from  $A(n)$  to  $B(m)$ , then the best change would be from  $A(n - 1)$  to  $B(m)$  plus one more deletion. That is:

$$C(n, m) = C(n - 1, m) + \textit{deletion\_cost}$$

insert:

if the minimum change from  $A(n)$  to  $B(m)$  involves insertion of a character to match  $b_m$ , then we have

$$C(n, m) = C(n, m - 1) + \textit{insertion\_cost}$$

That is, we find the minimum change from  $A(n)$  to  $B(m - 1)$  and insert a character equal to  $b_m$ .

replace:

if  $a_n$  is replacing  $b_m$ , then we first need to find the minimum change from  $A(n - 1)$  to  $B(m - 1)$  and then to add 1 if  $a_n \neq b_m$ . That is

$$C(n, m) = C(n - 1, m - 1) + \textit{replacement\_cost}$$

do nothing:

if  $a_n = b_m$ , then  $C(n, m) = C(n - 1, m - 1)$

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In short (assuming insertion cost, deletion cost, replacement cost is equal to 1),

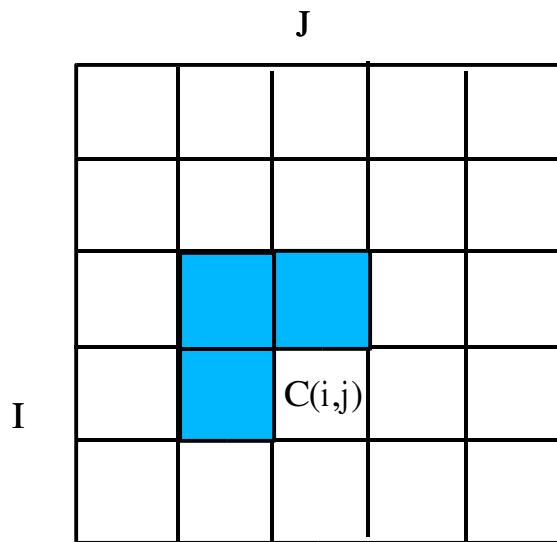
$$C(n, m) = \min \begin{cases} C(n-1, m) + \text{cost\_of\_deletion} & \text{deleting } a_n \\ C(n, m-1) + \text{cost\_of\_insertion} & \text{inserting for } a_n \\ C(n-1, m-1) + \text{cost\_of\_replacement} & \text{replacing } a_n \\ C(n-1, m-1) & \text{do\_nothing } a_n \end{cases}$$

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# The dependencies of $C(i,j)$



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## Approach: Dynamic Programming

**Algorithm Minimum\_Edit\_Distance**( $A, n, B, m$ )

**Input:**  $A$  (a string of size  $n$ ; and  
 $B$  (a string of size  $m$ )

**Output:**  $C$  (the cost matrix)

**begin**

**for**  $i = 0$  to  $n$  **do**  $C[i, 0] = i$ ;

**for**  $j = 1$  to  $m$  **do**  $C[0, j] = j$ ;

**for**  $i = 1$  to  $n$  **do**

**for**  $j = 1$  to  $m$  **do**

$x = C[i - 1, j] + \text{cost\_of\_deletion}$ ;

$y = C[i, j - 1] + \text{cost\_of\_insertion}$ ;

**if**  $a_i = b_j$  **then**

$z = C[i - 1, j - 1]$ ;

**else**

$z = C[i - 1, j - 1] + \text{cost\_of\_replacement}$ ;

$C[i, j] = \min(x, y, z)$ ;

**end.**

Reference Udi Manber page 158

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