

PHYSICS I: An Outline

Chap 1. Introduction

1. Significant Figures
2. Units (SI, British)

Chap 2. Kinematics -1D

1. Average, Instantaneous
2. Displacement, Velocity, Acceleration, Derivatives

$$\bar{v} = \frac{\Delta x}{\Delta t}, v = \frac{dv}{dt}$$

3. Uniform Acceleration

$$v = v_0 + at$$

$$x = x_0 + \bar{v}t, \bar{v} = \frac{1}{2}(v + v_0),$$

$$v^2 = v_0^2 + 2a(x - x_0),$$

$$x = x_0 + v_0t + \frac{1}{2}at^2.$$

4. Falling Bodies $a = -g$.

Chap 3. Vectors

1. Vectors and Scalars:

$$\mathbf{V} = V_x \mathbf{i} + V_y \mathbf{j} + V_z \mathbf{k}$$

2. Addition, Scalar Multiplication, Length

3. Components

$$V_x = V \cos \theta, V_y = V \sin \theta.$$

$$V = \sqrt{V_x^2 + V_y^2}, \tan \theta = \frac{V_y}{V_x}.$$

Chap 4. Kinematics - 2D-#D

1. Displacement, Velocity, Acceleration
 2. Projectile Motion
- $$a_x = 0, a_y = -g \quad g = 9.8 \text{ m/s}^2$$
3. Circular Motion: Uniform
- $$a_r = \frac{v^2}{r}, T = \frac{2\pi r}{v}, f = \frac{1}{T}$$

$$\text{Nonuniform: } a_r = \frac{dv}{dt}$$

Chap 5. Force and Motion I

1. Law of Inertia
2. $\mathbf{F}_{net} = m\mathbf{a}$
3. Action-Reaction
4. Weight, Normal Force, Tension $W = mg, N, T$
5. Free Body Diagrams

Chap 6. Force and Motion II

1. Friction $f = \mu_i N$
 2. Circular Motion
- $$a_r = \frac{v^2}{r}, F = ma_c$$
3. Unbanked Curves
- $$v = \sqrt{\mu_s g r}$$
4. Banked Curve $\tan \theta = \frac{v^2}{rg}$

Chap 7. Work and Energy

1. $W = \mathbf{F} \cdot \mathbf{d} = Fd \cos \theta$
 2. $W = \int_a^b \mathbf{F} \cdot d\mathbf{l}$
 3. $W = \Delta K, K = \frac{1}{2}mv^2$
 4. Hooke's Law $F = -kx$
 5. Power
- $$\bar{P} = \frac{W}{t}, P = \frac{dW}{dt} = \mathbf{F} \cdot \mathbf{v}$$

Chap 8. Energy Conservation

1. $U = mgy$ (gravitation),
 $U = \frac{1}{2}kx^2$ (spring)
2. $\Delta U = -\int_1^2 \mathbf{F} \cdot d\mathbf{l}, F = -\frac{dU}{dx}$
3. Conservation of Energy:
 $E = \frac{1}{2}mv^2 + U$

Chap 9. Linear Momentum

1. Center of Mass:
- $$\mathbf{r}_{com} = \frac{1}{M} \sum m_i \mathbf{r}_i,$$
- $$\mathbf{r}_{com} = \frac{1}{M} \int \mathbf{r} dm$$
2. Momentum $\mathbf{p} = m\mathbf{v}$
- $$M\mathbf{r}_{com} = \sum m_i \mathbf{r}_i,$$
- $$\mathbf{v}_{com} = \frac{1}{M} \sum m_i \mathbf{v}_i,$$
3. $\mathbf{F}_{ext} = M\mathbf{a}_{com}, \mathbf{F}_{ext} = \frac{d\mathbf{P}}{dt}$,
 4. Momentum Conservation
 5. Inelastic Collisions
 6. Elastic Collisions
- $$v_{if} = \frac{m_1 - m_2}{m_1 + m_2} v_{i1}$$
- $$v_{if} = \frac{2m_1}{m_1 + m_2} v_{i1}$$
7. Impulse: $J = \Delta mv = F\Delta t$

Chap 10. Rotation

1. Rotational Variables
 2. Kinematics
- $$\omega = \omega_0 + \alpha t,$$
- $$\theta = \omega_0 t + \frac{1}{2}\alpha t^2,$$
- $$\omega^2 = \omega_0^2 + 2\alpha\theta$$
3. $\omega = \frac{d\theta}{dt}, \alpha = \frac{d\omega}{dt}$
 4. Torque: $\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F} = I\boldsymbol{\alpha}$.
 5. Moment of Inertia
- $$I = mr^2, \text{ (particle) and rod, sphere, cylinder}$$
6. Kinetic Energy $K = \frac{1}{2}I\omega^2$
 7. Parallel Axis Theorem
- $$I = I_{com} + Mh^2$$

Chap 11. Angular Momentum

1. Rolling without Slipping
- $$v_{com} = \omega r$$
2. Angular Momentum:
- $$\mathbf{L} = \mathbf{r} \times \mathbf{p}, L = I\omega, \boldsymbol{\tau}_{net} = \frac{d\mathbf{L}}{dt}$$
3. Conservation Law $L_i = L_f$
 4. $K_{total} = K_{rot} + K_{trans}$
- $$\text{(Rolling Sphere} = \frac{7}{10}mv^2)$$

Chap 12. Equilibrium and Elasticity

1. $\sum \mathbf{F} = 0, \sum \boldsymbol{\tau} = 0$
2. Center of Gravity
3. Stress \propto Strain, $\frac{F}{A} = E \frac{\Delta L}{L}$
4. Linear, Shear, Bulk

Chap 13. Gravitation

1. $F = \frac{Gm_1 m_2}{r^2}, g = \frac{GM}{R^2}$

$$2. U = -\frac{GMm}{r}$$

3. Satellites $v = \sqrt{\frac{GM}{r}}$
 4. Kepler's Laws of Motion
- $$\text{(3rd } \frac{T^2}{r^3} = \frac{4\pi^2}{GM})$$

Chap 14. Fluids

1. $m = \rho V, p = \frac{F}{A}$
 2. $p = p_0 + \rho gh$
 3. Pascal's Principle $P_o = P_i$
 4. Archimedes' $B = \rho_i g V$
 5. Flow Rate: $R_v = Av$
 6. Continuity $A_1 v_1 = A_2 v_2$
 7. Bernoulli's Equation
- $$P + \frac{1}{2}\rho v^2 + \rho gh = \text{const.}$$

Chap 15. Oscillations

1. Hooke's Law $F = -kx$
 2. $m\ddot{x} + kx = 0 \Rightarrow \ddot{x} + \omega^2 x = 0$
 3. $x(t) = a \sin \omega t + b \cos \omega t,$
 $x(t) = A \cos(\omega t + \phi)$
 4. $\omega = \sqrt{\frac{k}{m}}$ (spring),
 $\omega = \sqrt{\frac{g}{L}}$ (pendulum)
 5. Energy
- $$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = \frac{1}{2}kA^2$$
6. Physical Pendulum
- $$T = 2\pi \sqrt{\frac{I}{mgh}}$$

Chap 16. Wave Motion

1. $v = \lambda f$
 2. $v = \sqrt{\frac{\tau}{\mu}}$ (string)
 3. $y = y_m \sin(kx \pm \omega t)$
 4. $k = \frac{2\pi}{\lambda}, \omega = \frac{2\pi}{T} = 2\pi f$
 5. Superposition, reflection, refraction, interference, diffraction, resonance
 6. Standing Waves - String
- $$\lambda_n = \frac{2L}{n}, n = 1, 2, \dots$$

Chap 17. Sound

1. $v = \sqrt{\frac{B}{\rho}}, v \approx 331 + 0.60T$
 2. loudness, pitch, range
 3. Intensity $I = \frac{P}{A} \propto \{A^2, \frac{1}{r^2}\}$
 4. Level: $\beta(\text{dB}) = 10 \log \frac{I}{I_0}$
 5. Open-Open/Closed Tubes
- $$f_n = \frac{nv}{2L}, f_n = \frac{nv}{4L}$$
6. Beats $f_{beat} = \Delta f$
 7. Doppler Effect
- $$f' = f \left(\frac{v \pm v_D}{v \pm v_S} \right) \text{ (toward - up)}$$
8. Shock Waves $\sin \theta = \frac{v}{v_s}$

Chap 18. Temperature, Thermal Expansion and the Ideal Gas Law

1. Temperature Scales
2. Expansion $\Delta L = \alpha L_0 \Delta T$
3. Heat Capacity, Latent Heat
 $Q = mc\Delta T, Q = mL$
4. Mechanical Equiv of Heat
5. $W = \int p dV$
6. 1st Law $U = Q - W$
7. isothermal, isobaric, isochoric, adiabatic
8. Conduction, $\frac{dQ}{dt} = -kA \frac{dT}{dx}$
9. Convection
10. Radiation, $\frac{\Delta Q}{\Delta t} = e\sigma AT^4$

Chap 19. Kinetic Theory

1. Molar mass
 2. $PV = nRT = NkT$
 3. Isothermal $W = nRT \ln \frac{V_2}{V_1}$
 4. $\frac{1}{2}(mv^2)_{ave} = \frac{3}{2}kT$
 $\Rightarrow v_{rms} = \sqrt{\frac{3kT}{m}}$
 5. $U = \frac{3}{2}nRT$
 6. $Q = nC\Delta T$
 7. $C_v = \frac{5}{2}R, C_p = C_v + R$
 8. Adiabatic
- $$pV^\gamma = \text{const}, \gamma = \frac{C_p}{C_v}$$

Chap 20. The Second Law of Thermodynamics

1. $\epsilon = \frac{W}{|Q_H|} = 1 - \frac{|Q_C|}{|Q_H|}$
 2. Carnot engines
- $$\epsilon_c = 1 - \frac{T_C}{T_H}$$
3. Kelvin-Planck, Clausius
 4. $\oint \frac{dQ}{T} = 0$ (reversible)
 5. Entropy: $dS = \frac{dQ}{T}$
 6. $\Delta S > 0$
 7. $S = k \ln W$

Miscellaneous Constants

- $$G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$$
- $$N_A = 6.02 \times 10^{23} \text{ mol}^{-1}$$
- $$R = 8.315 \text{ J/(mol}\cdot\text{K)}$$
- $$k = 1.38 \times 10^{-23} \text{ J/K}$$
- $$\sigma = 5.67 \times 10^{-8} \text{ W/(m}^2\cdot\text{K}^4)$$
- $$1 \text{ cal} = 4.186 \text{ J}$$
- $$1 \text{ atm} = 1.013 \times 10^5 \text{ Pa}$$
- $$L_f = 80 \text{ cal/g}, L_v = 540 \text{ cal/g}$$
- $$\rho_{water} = 1.0 \times 10^3 \text{ kg/m}^3$$
- $$v_{air} = 331 \text{ m/s (0}^\circ\text{C)}$$
- $$I_0 = 1.0 \times 10^{-12} \text{ W/m}^2$$
- $$c_{water} = 1.0 \text{ kcal/(kg}\cdot\text{C)}$$