

# PHY 101 College Physics Outline

## Ch. 1. Introduction

1. Significant figures.
2. Units (MKS, CGS, British).
3. Dimensional Analysis.
4. Trigonometry:  $\sin \theta = \frac{\text{opp}}{\text{hyp}}$ ,  
 $\cos \theta = \frac{\text{adj}}{\text{hyp}}$ ,  $\tan \theta = \frac{\text{opp}}{\text{adj}}$ .
5. Vectors and Scalars.
6. Vector Addition.
7. Vector Components,  
 $V_x = V \cos \theta$ ,  $V_y = V \sin \theta$ ,  
 $V = \sqrt{V_x^2 + V_y^2}$ ,  $\tan \theta = \frac{V_y}{V_x}$ .

## Ch. 2. Kinematics-1D

1. Displacement, velocity, acceleration.
2. Average, Instantaneous values.
3.  $\bar{v} = \frac{\Delta x}{\Delta t}$ ,  $v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$ .
4. Uniform acceleration,
5. Kinematic Equations,  $v = v_0 + at$ ,  
 $x = \bar{v}t$ ,  $\bar{v} = \frac{1}{2}(v_0 + v)$ ,  
 $v^2 = v_0^2 + 2ax$ ,  $x = v_0t + \frac{1}{2}at^2$ .
6. Free fall,  $a = -g$ .

## Ch. 3. Kinematics-2D

1. Displacement, Velocity, Acceleration
2. Projectile Motion ( $a_x = 0$ ,  $a_y = -g$ )

## Ch. 4. Forces and Newton's Laws of Motion

1. Law of Inertia, Mass.
2.  $F = ma$ .
3. Action-Reaction.
4. Gravitational Force,  
$$F = G \frac{m_1 m_2}{r^2}$$
5. Weight, Normal force,  
 $W = mg$ ,  $N$ ,  $g = \frac{GM}{R^2}$ .
6. Apparent Weight,  $W_{app} = m(g + a)$ .
7. Vector Forces, Free Body Diagrams.
8. Friction  $f = \mu_s N$ .
9. Equilibrium and Non-equilibrium,

$$\sum \mathbf{F} = \mathbf{0}, \quad \sum \mathbf{F} = m\mathbf{a}$$

## Ch. 5. Uniform Circular Motion

1. Circular Motion,  $v = \frac{2\pi r}{T}$ .
2. Centripetal Acceleration,  
 $a_c = \frac{v^2}{r}$ ,  $F_c = \frac{mv^2}{r}$ .
3. Banked Curves,  $\tan \theta = \frac{v^2}{rg}$ .
4. Circular Orbits,  $v = \sqrt{\frac{GM}{R}}$ .
5. Weightlessness.

## Ch. 6. Work and Energy

1.  $W = \mathbf{F} \cdot \mathbf{d} = Fd \cos \theta$ .
2.  $W = \Delta KE$ ,  $KE = \frac{1}{2}mv^2$ .
3.  $PE = mgh$ , (gravitation).
4. Conservation of Energy,  
$$E = \frac{1}{2}mv^2 + mgh = \text{const.}$$
5. Power,  $\bar{P} = \frac{W}{t}$ ,  $P = Fv$ .

## Ch. 7. Impulse and Momentum

1. Momentum,  $\mathbf{p} = m\mathbf{v}$ .
2. Impulse,  $\mathbf{I} = \mathbf{F}\Delta t = \Delta\mathbf{p}$ .
3. Conservation of Linear Momentum.
4. Elastic/Inelastic Collisions.

## Ch. 8. Rotational Kinematics

1. Arclength,  $s = r\theta$ .
2. Kinematics,  $\omega = \omega_0 + \alpha t$ ,  $\theta = \bar{\omega}t$ ,  
 $\bar{\omega} = \frac{1}{2}(\omega_0 + \omega)$ ,  
 $\omega^2 = \omega_0^2 + 2\alpha\theta$ ,  $\theta = \omega_0 t + \frac{1}{2}\alpha t^2$ .
3. Centripetal/Tangential Acceleration,  
 $a + t = r\alpha$ .
4. Rolling motion,  $v = r\omega$ .

## Ch. 9. Rotational Dynamics

1. Torque,  $\tau = Fl = I\alpha$ .
2. Moments of Inertia,  $I = mr^2$  (particle), and rod, sphere, hoop, cylinder.
3. Parallel Axis Theorem.
4. Center of Gravity.
5. Angular Momentum,  $L = I\omega$ .

6. Kinetic Energy,  $KE_{\text{rot}} = \frac{1}{2}I\omega^2$ ,  
 $KE = KE_{\text{trans}} + KE_{\text{rot}}$ . Rolling sphere,  $KE = \frac{7}{10}mv^2$ .
7. Equilibrium,

$$\sum \mathbf{F} = \mathbf{0}, \quad \sum \tau = 0.$$

## Ch. 10. Elasticity and Simple Harmonic Motion

1. Stress =  $\frac{F}{A}$ , Strain =  $\frac{\Delta L}{L_0}$ .
2. Elastic Moduli
3. Springs,  $F = -kx$ ,  $\omega = \sqrt{\frac{k}{m}}$ ,  
 $PE = \frac{1}{2}kx^2$ .
4. Pendula,  $\omega = \sqrt{\frac{g}{L}}$ .

## Ch. 11. Fluids

1.  $m = \rho V$ ,  $P = \frac{F}{A}$ .
2.  $P = P_0 + \rho gh$ .
3. Pascal's Principle,  $P_o = P_i$ .
4. Archimede's Principle,  $B = \rho_f gh$ .
5. Flow Rate,  $Q = Av$ .
6. Bernoulli's Equation,

$$P + \frac{1}{2}\rho v^2 + \rho gh = \text{const.}$$

## Ch. 12. Temperature, Thermal Expansion, and Heat energy

1. Temperature Scales.
2. Thermal Expansion,  $\Delta L = \alpha L_0 \Delta T$ .
3.  $Q = mc\Delta T$ ,  $Q = mL$ .

## Ch. 13. The Transfer of Heat

1. Conduction,  $Q = \frac{kA\Delta T t}{L}$ .
2. Convection.
3. Radiation,  $Q = \epsilon\sigma AT^4$ .

## Ch. 14. Ideal Gas Law and Kinetic Theory

1.  $PV = nRT = NkT$ .
2.  $\frac{1}{2}(mv^2)_{\text{ave}} = \frac{3}{2}kT \Rightarrow v_{\text{rms}} = \sqrt{\frac{3kT}{m}}$ .
3.  $U = \frac{3}{2}nRT = \frac{3}{2}NkT$ .

## Ch. 15. Thermodynamics

1.  $W = P\Delta V$ ,  $W = nRT \ln \frac{V_2}{V_1}$
2. 1st Law,  $\Delta U = Q - W$ .
3.  $Q = nC\Delta T$ .
4.  $C_p - C_v = R$ ,  $\gamma = C_p/C_v$ .
5. Isothermal, isobaric, isochoric, adiabatic.
6.  $PV^\gamma = \text{const}$  (adiabatic).
7. 2nd Law,  $\Delta S \geq 0$ .
8.  $e = \frac{W}{Q_H} = 1 - \frac{Q_C}{Q_H}$ ,  $e_{\text{max}} = 1 - \frac{T_C}{T_H}$ .
9. Carnot Engines (reversible).
10. Entropy:  $S = \frac{\Delta Q}{T}$ .

## Ch. 16. Waves and Sound

1.  $v = f\lambda$ .
2.  $v = \sqrt{\frac{F}{\mu}}$  (string).
3.  $v = \sqrt{\frac{B}{\rho}}$ ,  $v \approx 331 + 0.60T$ .
4. Loudness, pitch, audible range.
5. Intensity,  $I = \frac{\bar{P}}{A} \propto A^2, \frac{1}{r^2}$ .
6.  $\beta(\text{dB}) = 10 \log \frac{I}{I_0}$ .
7.  $y = A \sin(kx \pm \omega t)$ ,  
 $k = \frac{2\pi}{\lambda}$ ,  $\omega = \frac{2\pi}{T} = 2\pi f$ .
8. Doppler Effect,  $f' = \frac{v \pm v_o}{v - v_s} f$  (towards).

## Ch. 17. Superposition and Interference

1. Superposition, reflection, refraction, diffraction.
2. Diffraction,  $\lambda = D \sin \theta$ .
3. Standing Waves, string,  $f = n \frac{v}{2L}$ ,  
 $n = 1, 2, \dots$
4. Standing Waves, open/closed tubes.

## Constants

1.  $g = 9.8 \text{ m/s}^2$
2.  $G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$
3.  $N_A = 6.02 \times 10^{23} \text{ mol}^{-1}$
4.  $R = 8.315 \text{ J}/(\text{mol}\cdot\text{K})$
5.  $k = 1.38 \times 10^{-23} \text{ J/K}$
6.  $\sigma = 5.67 \times 10^{-8} \text{ W}/(\text{m}^2\cdot\text{K}^4)$
7.  $1 \text{ cal} = 4.184 \text{ J}$ .
8.  $1 \text{ atm} = 1.013 \times 10^5 \text{ N/m}^2$
9.  $L_f = 80 \text{ kcal/kg}$ ,  $L_v = 540 \text{ kcal/kg}$ .