

PHYSICS I: An Outline

<p>Chap 1. Introduction</p> <ol style="list-style-type: none"> Significant Figures Units (MKS, CGS, SI, British) Dimensional Analysis Trigonometry $\sin \theta = \frac{\text{opp}}{\text{hyp}}, \cos \theta = \frac{\text{adj}}{\text{hyp}},$ $\tan \theta = \frac{\text{opp}}{\text{adj}}$ Vectors and Scalars $\mathbf{V} = V_x \mathbf{i} + V_y \mathbf{j} + V_z \mathbf{k}$ Vector Addition Vector Components $V_x = V \cos \theta, V_y = V \sin \theta$ $V = \sqrt{V_x^2 + V_y^2}, \tan \theta = \frac{V_y}{V_x}$ <p>Chap 2. Kinematics -1D</p> <ol style="list-style-type: none"> Average, Instantaneous Displacement, velocity, acceleration, derivatives $\bar{v} = \frac{\Delta x}{\Delta t}, v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$ Uniform Acceleration $v = v_0 + at, \bar{v} = \frac{1}{2}(v + v_0),$ $v^2 = v_0^2 + 2ax,$ $x = v_0 t + \frac{1}{2}at^2.$ Falling Bodies $a = -g$. <p>Chap 3. Kinematics - 2D</p> <ol style="list-style-type: none"> Displacement, Velocity, Acceleration Projectile Motion ($a_x = 0, a_y = -g$). <p>Chap 4. Forces and Newton's Laws of Motion</p> <ol style="list-style-type: none"> Law of Inertia, Mass $F = ma$ Action-Reaction Gravitational Force $F = \frac{Gm_1m_2}{r^2}$ Weight, Normal Force $W = mg, N, g = \frac{GM}{R^2}$ Apparent Weight $F_{app} = m(g + a)$ Vector Forces, Free Body Diagrams Friction $f = \mu_s N$ Equilibrium and Non-Equilibrium $\Sigma \mathbf{F} = \mathbf{0}, \Sigma \mathbf{F} = m\mathbf{a}$ 	<p>Chap 5. Dynamics of Uniform Circular Motion</p> <ol style="list-style-type: none"> Circular Motion $v = \frac{2\pi r}{T}$ Centripetal Acceleration $a_C = \frac{v^2}{r}, F_C = \frac{mv^2}{r}$ Banked Curves $\tan \theta = \frac{v^2}{rg}$ Circular Orbits $v = \sqrt{\frac{GM}{R}}$ Weightlessness <p>Chap 6. Work and Energy</p> <ol style="list-style-type: none"> $W = \mathbf{F} \cdot \mathbf{d} = Fd \cos \theta$ $W = \Delta KE, KE = \frac{1}{2}mv^2$ $PE = mgh$ (gravitation) Conservation of Energy: $E = \frac{1}{2}mv^2 + mgh = \text{const}$ Power $\bar{P} = \frac{W}{t}, P = Fv$ <p>Chap 7. Impulse and Momentum</p> <ol style="list-style-type: none"> Momentum $\mathbf{p} = m\mathbf{v}$ Impulse $\mathbf{I} = \bar{\mathbf{F}}\Delta t = \Delta \mathbf{p}$ Conservation of Linear Momentum, collisions <p>Chap 8. Rotational Kinematics</p> <ol style="list-style-type: none"> Arclength $s = r\theta$ Kinematics $\omega = \omega_0 + \alpha t,$ $\theta + \omega_0 t + \frac{1}{2}\alpha t^2,$ $\omega^2 = \omega_0^2 + 2\alpha\theta$ Centripetal/Tangential Acceleration $a_T = r\alpha$ Rolling motion $v = r\omega$ Conservation of Linear Momentum, collisions <p>Chap 9. Rotational Dynamics</p> <ol style="list-style-type: none"> Torque: $\tau = Fl = I\alpha$. Moment of Inertia $I = mr^2,$ (particle) and rod, sphere, cylinder Parallel Axis Theorem Center of Gravity Angular Momentum: $L = I\omega$ Kinetic Energy $KE_{rot} = \frac{1}{2}I\omega^2$ $KE_{rot} + KE_{trans}$ (Rolling Sphere = $\frac{7}{10}mv^2$) Equilibrium $\Sigma \mathbf{F} = \mathbf{0}, \Sigma \mathbf{t} = \mathbf{0}$ 	<p>Chap 10. Elasticity and Simple Harmonic Motion</p> <ol style="list-style-type: none"> stress = $\frac{F}{A}$, strain = $\frac{\Delta L}{L_0}$ Elastic Moduli Springs $F = -kx, \omega = \sqrt{\frac{k}{m}}$, $PE = \frac{1}{2}kx^2$ Pendula $\omega = \sqrt{\frac{g}{L}}$ <p>Chap 11. Fluids</p> <ol style="list-style-type: none"> $m = \rho V, P = \frac{F}{A}$ $P = P_0 + \rho gh$ Pascal's Principle $P_o = P_i$ Archimedes' Principle $B = \rho_f g V$ Flow rate: $Q = Av$ Continuity Bernoulli's Equation $P + \frac{1}{2}\rho v^2 + \rho gh = \text{const.}$ <p>Chap 12. Temperature, Thermal Expansion and the Ideal Gas Law</p> <ol style="list-style-type: none"> Temperature Scales Expansion $\Delta L = \alpha L_0 \Delta T,$ $\Delta V = \beta V_0 \Delta T$ $Q = mc\Delta T, Q = mL$ <p>Chap 13. The Transfer of Heat</p> <ol style="list-style-type: none"> Conduction $Q = \frac{kA\Delta T}{L}t$ Convection Radiation $Q = e\sigma AT^4 t$ <p>Chap 14. Ideal Gas Law and Kinetic Theory</p> <ol style="list-style-type: none"> $PV = nRT = NkT$ $\frac{1}{2}(mv^2)_{ave} = \frac{3}{2}kT$ $\Rightarrow v_{rms} = \sqrt{\frac{3kT}{m}}$ $U = \frac{3}{2}nRT = \frac{3}{2}NkT$ <p>Chap 15. Thermodynamics</p> <ol style="list-style-type: none"> $W = P\Delta V, W = nRT \ln \frac{V_2}{V_1}$ 1st Law $\Delta U = Q - W$ $Q = nC\Delta T$ $C_p - C_v = R, \gamma = \frac{C_p}{C_v}$ isothermal, isobaric, isochoric, adiabatic $PV^\gamma = \text{const}$ (adiabatic) 2nd Law $e = \frac{W}{Q_H} = 1 - \frac{Q_C}{Q_H} = 1 - \frac{T_C}{T_H}$ Carnot engines (reversible) 	<p>10. Entropy: $S = \frac{\Delta Q}{T} \Delta S > 0$</p> <p>Chap 16. Waves and Sound</p> <ol style="list-style-type: none"> $v = f\lambda$ $v = \sqrt{\frac{F}{\mu}}$ (string) $v = \sqrt{\frac{B}{\rho}}, v \approx 331 + 0.60T$ loudness, pitch, audible range Intensity $I = \frac{\bar{P}}{A} \propto \{A^2, \frac{1}{r^2}\}$ $\beta(\text{dB}) = 10 \log \frac{I}{I_0}$ $y = A \sin(kx \pm \omega t)$ $k = \frac{2\pi}{\lambda}, \omega = \frac{2\pi}{T} = 2\pi f$ Doppler Effect $f' = f \left(\frac{v \pm v_o}{v \mp v_s} \right)$ (signs - towards) <p>Chap 17. Superposition and Interference</p> <ol style="list-style-type: none"> Superposition, reflection, refraction, interference Diffraction $\lambda = D \sin \theta$ Standing Waves - String $f = n \frac{v}{2L}, n = 1, 2, \dots$ Standing Waves - open and closed tubes <p>Miscellaneous Constants</p> $g = 9.8 \text{ m/s}^2$ $G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$ $N_A = 6.02 \times 10^{23} \text{ mol}^{-1}$ $R = 8.315 \text{ J/(mol}\cdot\text{K)}$ $k = 1.38 \times 10^{-23} \text{ J/K}$ $\sigma = 5.67 \times 10^{-8} \text{ W/(m}^2\cdot\text{K}^4)$ $1 \text{ cal} = 4.184 \text{ J}$ $0^\circ\text{K} = -273.15^\circ\text{C}$ $1 \text{ atm} = 1.013 \times 10^5 \text{ N/m}^2$ $L_f = 80 \text{ kcal/kg}$ $L_v = 540 \text{ kcal/kg}$ $\rho_{water} = 1.0 \times 10^3 \text{ kg/m}^3$ $\rho_{air} = 1.29 \text{ kg/m}^3$ $v_{air} = 331 \text{ m/s } (0^\circ\text{C})$ $v_{air} = 343 \text{ m/s } (20^\circ\text{C})$ $I_0 = 1.0 \times 10^{-12} \text{ W/m}^2$ $c_{water} = 1.0 \text{ kcal/(kg}\cdot^\circ\text{C)}$
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